

## ARTICULATED articc3-1943-30kg

Article number: AT\_30006



### **Description :**

This type of robot is based on the principle of serial kinematics. All drives and motor cables, except the stationary axis 1, are moved along. The robot has two (2) translational and one (1) rotational degree(s) of freedom.

### **Scope of delivery:**

Robot mechanics incl. gearbox, Free installation of drive technology provided (including incoming goods inspection), Multi-hour, logged test run as final quality inspection, Threaded protection caps , Transport and packing instructions

### **Required accessories:**

Set of parts for installing the drive technology. This set consists of, for example, a servo motor adapter, servo motor cable, transmission input pinion, plug board (usually on the base frame).

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## Technical specifications:

Field of application	Standard (not hygienic), CNC Robotics
Kinematics	Serial
Translatory Degrees of Freedom (X,Y,Z)	2
Rotational Degrees of Freedom ( $\alpha, \beta, \gamma$ )	1
Nominal payload [kg   lbs] *	30   66.1
Supplementary load on the arm [kg   lbs]	40   88.2
Working area-reach [mm   in]	1943   76.5
Lubricants of the bearings	Synthetic
Lubricants of the gearboxes	Synthetic
Cleaning	No high pressure
Protection class	IP64
Ambient temperature [°C   °F]	0 to +40   +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall, Angle
Robot weight without drive engineering (esp. drive) [kg   lbs]	150   330.7

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.