

Depending on the motor type

Maximum deflection of the upper arm

A (2:1)

Flange diagram according to ISO 9409-1-40-4-M6

Kinematic center point  
(within the plane of the axes)

Motion range in correlation to the Kinematic center point

Interference contour from machine body

Maximum interference contour

**Tool Center Point**  
TCP (on the plane of the flange)

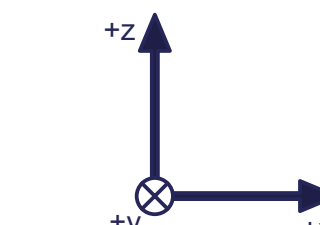
TCP - working range

Depending on the motor type

Z (1:2)

Kinematic center point  
(within the plane of the axes)

TCP



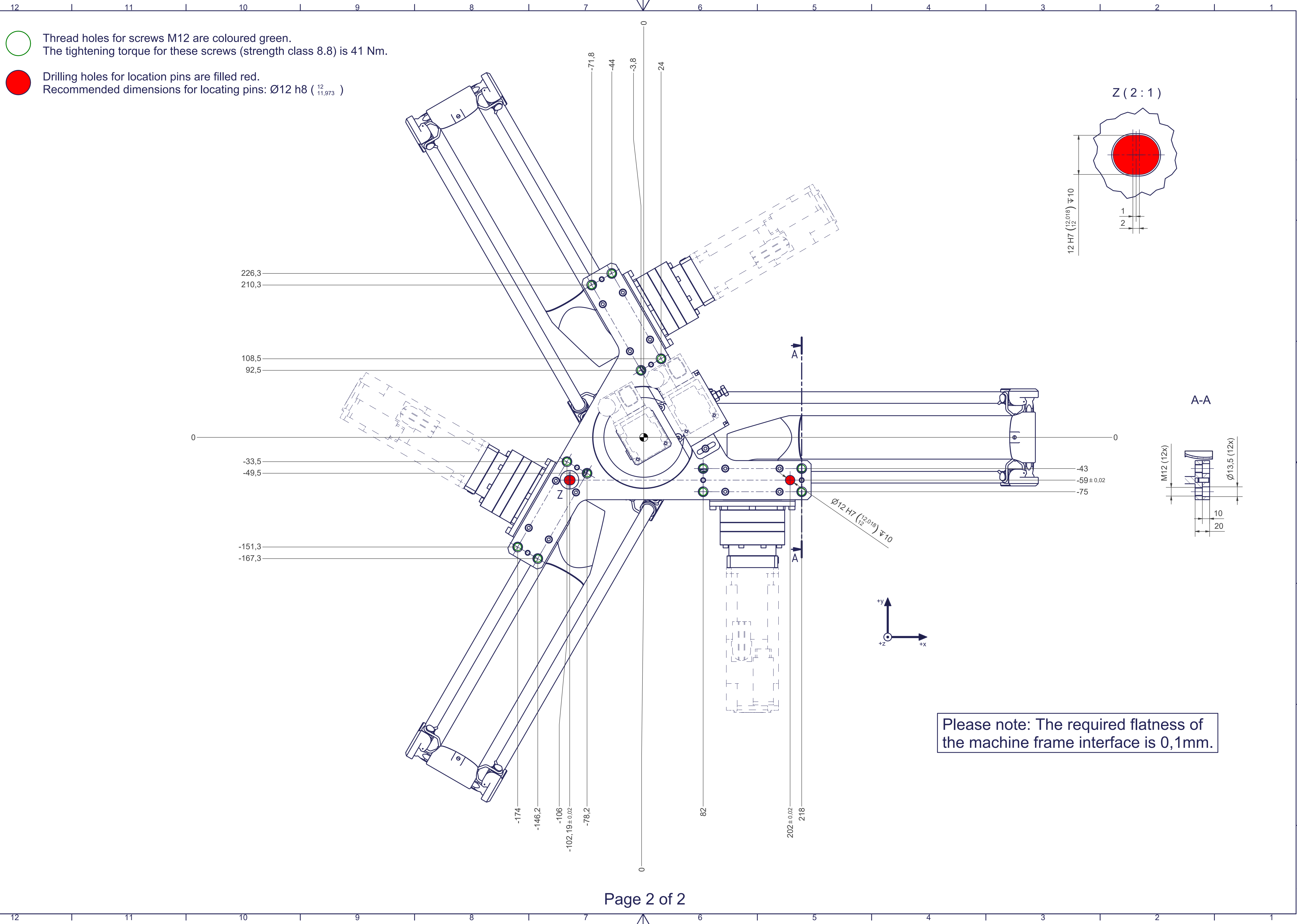
max. 93°

max. 3°

0°

Connecting dimensions,  
valid for article number AL\_00106

m= kg	A	p= bar
proj. storage surface = m²	P= kW	v̇= l/min
First angle projection	U= V / Hz / Ph	<b>autonox</b> lean line
I <sub>max</sub> =	A	



Please note: The required flatness of the machine frame interface is 0,1mm.