



Depending on the drive type

Maximum deflection of the upper arm

A (1:1)

Flange diagram according to ISO 9409-1-63-4-M6

Kinematic center point (within the plane of the axes)

Motion range in correlation to the Kinematic center point

Interference contour from machine body

Maximum interference contour

Tool Center Point TCP (on the plane of the flange)

TCP - working range

Kinematic center point (within the plane of the axes)

A4-axis (output)

A5-axis (output)

C (1:1)

Depending on the drive type

Connecting dimension, valid for article number A\_00819.01

m= kg	A	p= bar
proj. storage surface = m²		v̇= l/min
First angle projection	P= kW	U= V / Hz / Ph
	U= V / Hz / Ph	Imax= A



A\_00819.01

