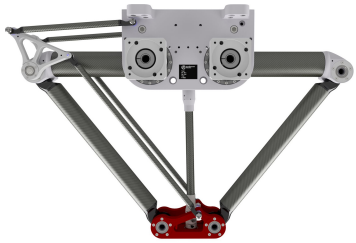
DuoPod RVS2-T1-750-15kg



Article number: A_00922-T1

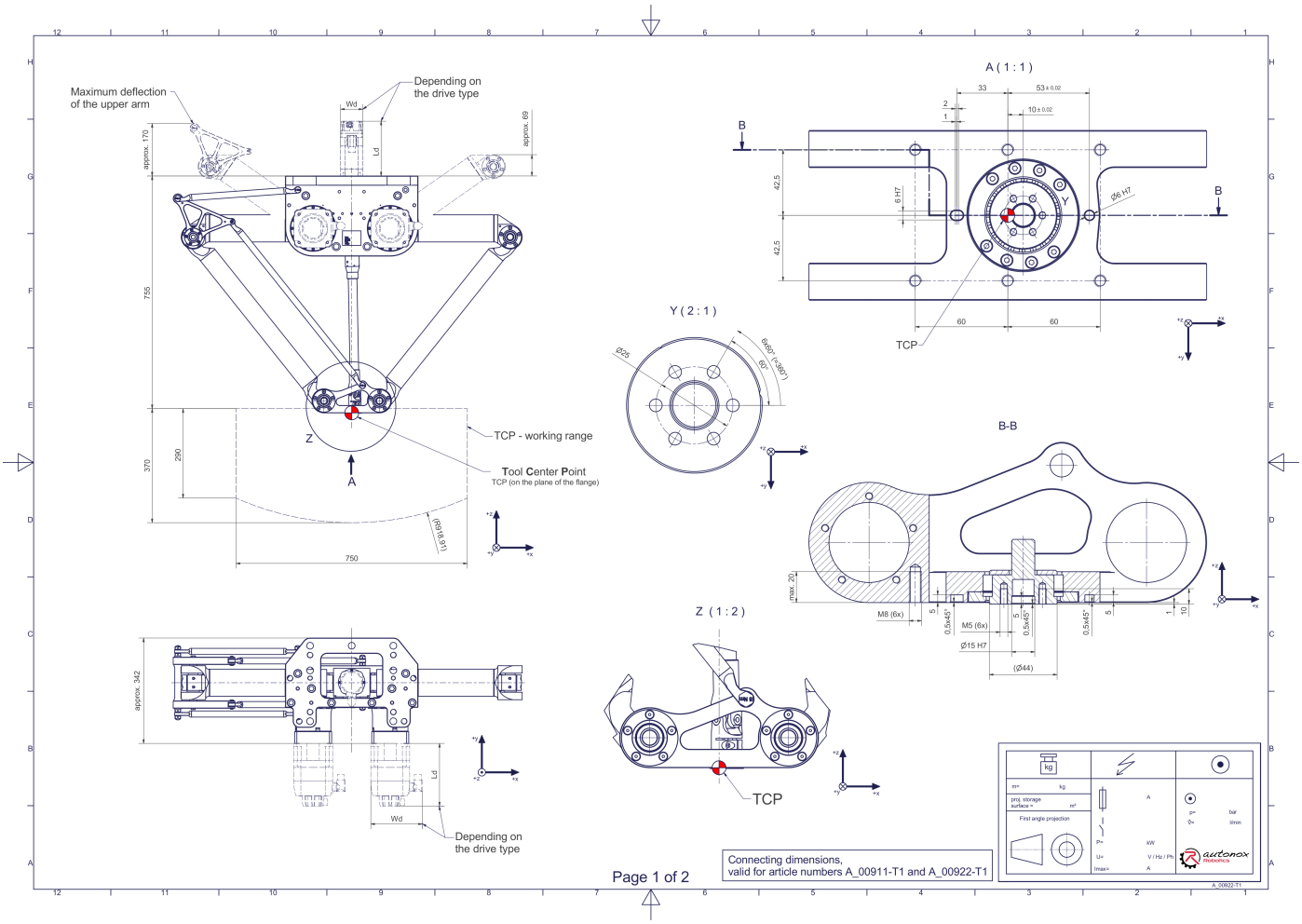
Mirror-inverted variant: No

Lubricant variant: Synthetic lubricants

Description:
This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has two (2) translational degrees of freedom.

Scope of delivery:
Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps , Transport and packing instructions

Connecting dimensions:



Downloads: Connecting dimensions (PDF) 3D model (STP) 3D model (PDF)

Technical specifications:

Field of application	Standard (not hygienic)
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	2
Rotational Degrees of Freedom (α,ß,γ)	0
Nominal payload [kg|lbs] *	15 | 33.1
Working area-width [mm|in]	750 | 29.5
Working height outside [mm|in]	290 | 11.4
Working height center [mm|in]	370 | 14.6
Output type of the tool actuation	Flange (T)
Number of the tool actuation (telescopic shaft(s))	1
Max. acceleration torque of the tool actuation T/TS1 at the output [Nm|in.lbs]	26,8 | 237.2
Nominal torque of the tool actuation T/TS1 at the output [Nm|in.lbs]	26,8 | 237.2
Max. speed of the tool actuation T/TS1 at the output [1/min]	750
Nominal speed of the tool actuation T/TS1 at the output [1/min]	400
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Synthetic
Lubricants of the gearboxes	Synthetic
Cleaning	No high pressure
Ambient temperature [°C|°F]	0 to +40 | +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)
Robot weight without drive engineering (esp. drive) [kg|lbs]	53 | 116.8

* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.