

## DuoPod RVS2-750-15kg

Article number: A\_00922-FO

### Mirror-inverted variant: No

**Lubricant variant:** Food-grade lubricants (FO)



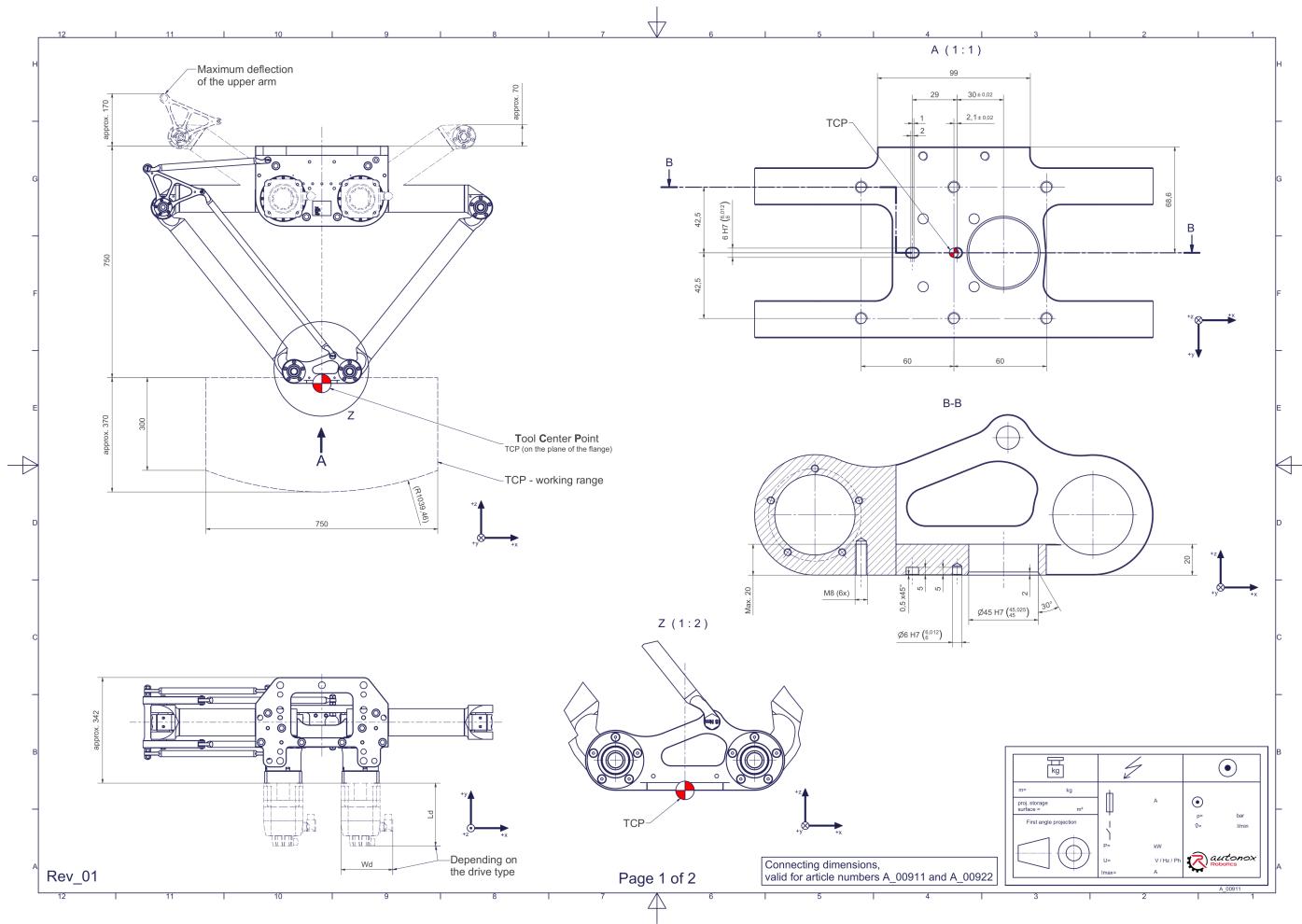
**Description:**

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has two (2) translational degrees of freedom.

### Scope of delivery:

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps , Transport and packing instructions

### Connecting dimensions:



**Downloads:** [Connecting dimensions \(PDF\)](#) [3D model \(STP\)](#) [3D model \(PDF\)](#)

We refer to our [General Terms of Sale and Supply](#) and [Terms of use](#).

**Technical specifications:**

<b>Field of application</b>	Standard (not hygienic)
<b>Kinematics</b>	Parallel
<b>Translatory Degrees of Freedom (X,Y,Z)</b>	2
<b>Rotational Degrees of Freedom (α,β,γ)</b>	0
<b>Nominal payload [kg   lbs] *</b>	15   33.1
<b>Working area-width [mm   in]</b>	750   29.5
<b>Working height outside [mm   in]</b>	300   11.8
<b>Working height center [mm   in]</b>	370   14.6
<b>Bearing type of the arm joints</b>	Roller bearing
<b>Lubricants of the bearings</b>	Food-grade (FO)
<b>Lubricants of the gearboxes</b>	Food-grade (FO)
<b>Cleaning</b>	No high pressure
<b>Ambient temperature [°C   °F]</b>	0 to +40   +32 to +104
<b>Relative humidity level [%]</b>	95 (free of condensation)
<b>Mounting position</b>	Floor, Ceiling, Wall (on request), Angle (on request)
<b>Robot weight without drive engineering (esp. drive) [kg   lbs]</b>	49   108.0

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

**Gearbox article number for this robot mechanics:**

Function	Article number	Document
Drive of the upper arms	MT_BGR00015048-xx-FO	Operating manual gearbox type 3 (PDF)