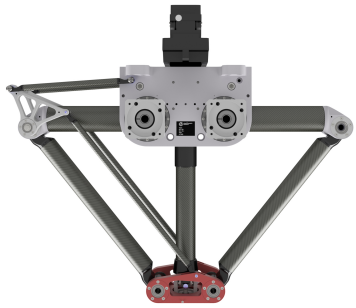
DuoPod RVS3-T1-750-12kg



Article number: A_00921-T1-FO

Lubricant variant: Food-grade lubricants (FO)

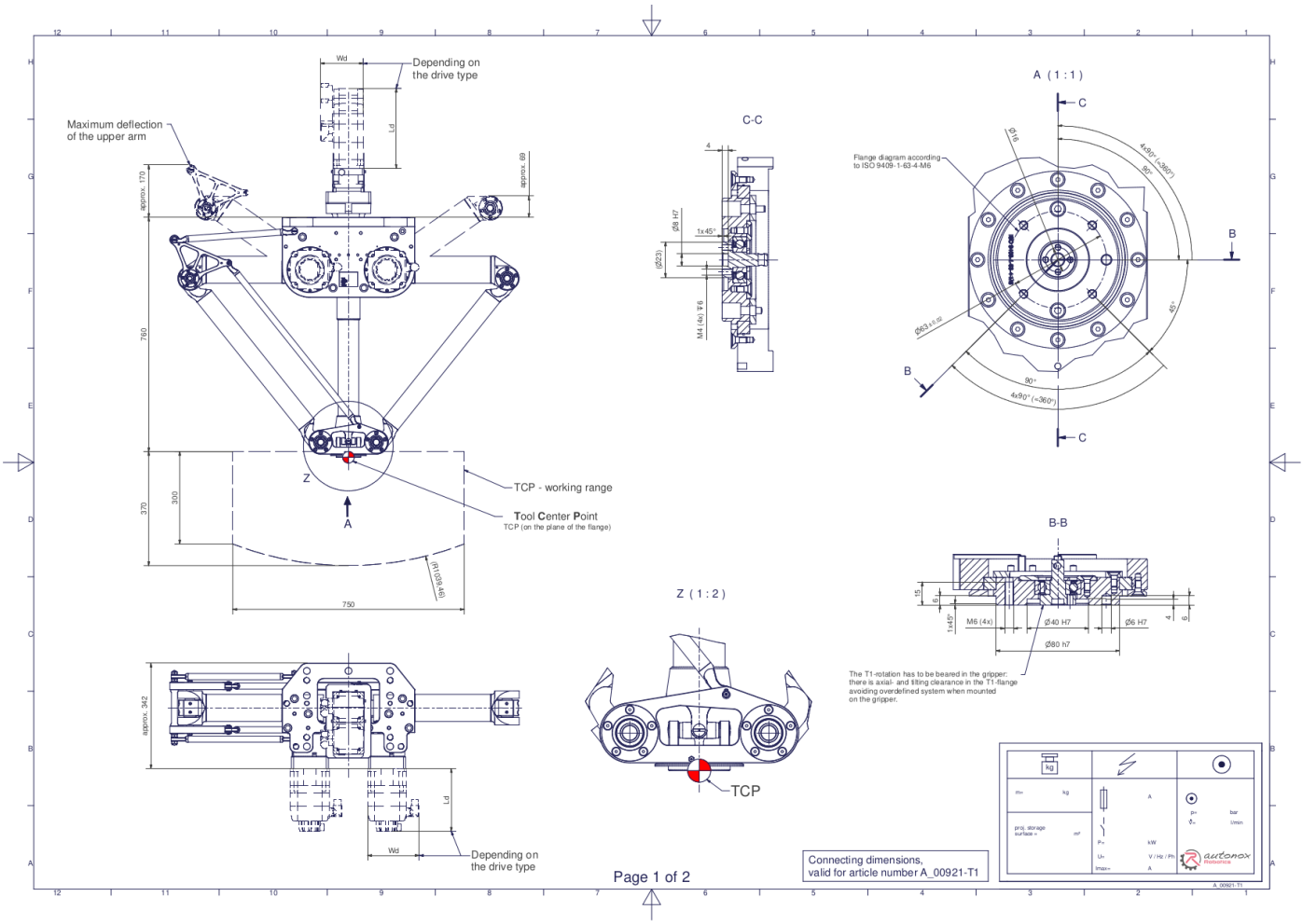
Description:

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has two (2) translational and one (1) rotational degree(s) of freedom.

Scope of delivery:

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps , Transport and packing instructions

Connecting dimensions:



Downloads: Connecting dimensions (PDF) 3D model (STP) 3D model (PDF)

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Technical specifications:

Field of application	Standard (not hygienic)
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	2
Rotational Degrees of Freedom (α,ß,γ)	1
Nominal payload [kg|lbs] *	12 | 26.5
Working area-width [mm|in]	750 | 29.5
Working height outside [mm|in]	300 | 11.8
Working height center [mm|in]	370 | 14.6
Output type of the tool actuation	Flange (T)
Number of the tool actuation (telescopic shaft(s))	1
Max. acceleration torque of the rotation γ around Z at the output [Nm|in.lbs]	40 | 354.0
Nominal torque of the rotation γ around Z at the output [Nm|in.lbs]	40 | 354.0
Max. speed of the rotation γ around Z at the output [1/min]	260
Nominal speed of the rotation γ around Z at the output [1/min]	160
Max. acceleration torque of the tool actuation T/TS1 at the output [Nm|in.lbs]	5,5 | 48.7
Nominal torque of the tool actuation T/TS1 at the output [Nm|in.lbs]	5,5 | 48.7
Max. speed of the tool actuation T/TS1 at the output [1/min]	800
Nominal speed of the tool actuation T/TS1 at the output [1/min]	800
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Food-grade (FO)
Cleaning	No high pressure
Ambient temperature [°C|°F]	0 to +40 | +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)

* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

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