

DuoPod RVS2-750-3kg

Article number: A_00911-MV-FO Mirror-inverted variant: Yes Lubricant variant: Food-grade lubricants (FO)



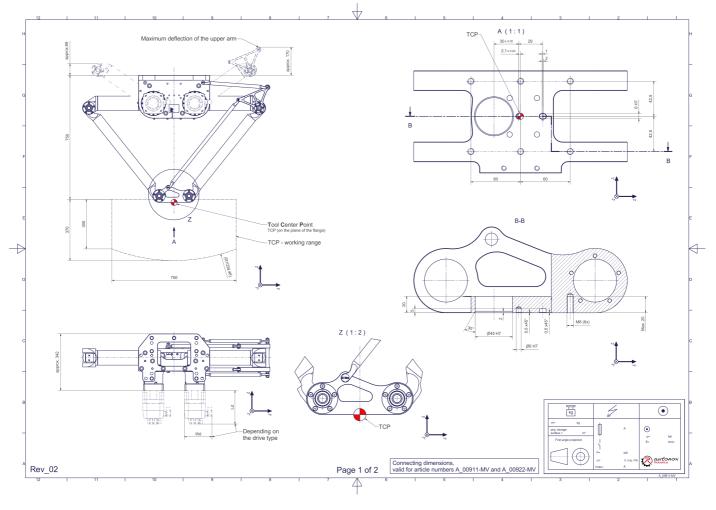
Description:

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has two (2) translational degrees of freedom. The article number extension '**MV**' (**M**irrored **V**ersion) identifies the mirrored version of the mechanics.

Scope of delivery:

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps, Transport and packing instructions

Connecting dimensions:



Downloads: Connecting dimensions (PDF) 3D model (STP) 3D model (PDF)

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Technical specifications:

| Field of application | Standard (not hygienic) |
|--|---|
| Kinematics | Parallel |
| Translatory Degrees of Freedom (X,Y,Z) | 2 |
| Rotational Degrees of Freedom (α, β, γ) | 0 |
| Nominal payload [kg lbs] * | 3 6.6 |
| Working area-width [mm in] | 750 29.5 |
| Working height outside [mm in] | 300 11.8 |
| Working height center [mm in] | 370 14.6 |
| Bearing type of the arm joints | Roller bearing |
| Lubricants of the bearings | Food-grade (FO) |
| Lubricants of the gearboxes | Food-grade (FO) |
| Cleaning | No high pressure |
| Ambient temperature [°C °F] | 0 to +40 +32 to +104 |
| Relative humidity level [%] | 95 (free of condensation) |
| Mounting position | Floor, Ceiling, Wall (on request), Angle (on request) |
| Robot weight without drive engineering (esp. drive) [kg lbs] | 49 108.0 |

* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

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