



## Technical specifications:

Field of application	Standard (not hygienic)
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	2
Rotational Degrees of Freedom ( $\alpha, \beta, \gamma$ )	1
Nominal payload [kg   lbs] *	6   13.2
Working area-width [mm   in]	1250   49.2
Working height outside [mm   in]	400   15.7
Working height center [mm   in]	535   21.1
Max. acceleration torque of the rotation $\beta$ around Y at the output [Nm   in.lbs]	135   1194.9
Nominal torque of the rotation $\beta$ around Y at the output [Nm   in.lbs]	135   1194.9
Max. speed of the rotation $\beta$ around Y at the output [1/min]	77
Nominal speed of the rotation $\beta$ around Y at the output [1/min]	77
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Synthetic
Lubricants of the gearboxes	Synthetic
Cleaning	No high pressure
Ambient temperature [°C   °F]	0 to +40   +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)
Robot weight without drive engineering (esp. drive) [kg   lbs]	65   143.3

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

## Gearbox article number for this robot mechanics:

Function	Article number	Document
Drive of the upper arms	MT_BGR00017292-U-xx	Operating manual gearbox type 3 (PDF)