

## Product data sheet <a href="https://autonoxfinder.com/en/A\_00875">https://autonoxfinder.com/en/A\_00875</a>

Date of download: Dec 24, 2025 Time of download: 13:55 UTC

### DELTA RL3-800-1kg

Article number: A\_00875

Lubricant variant: Synthetic lubricants



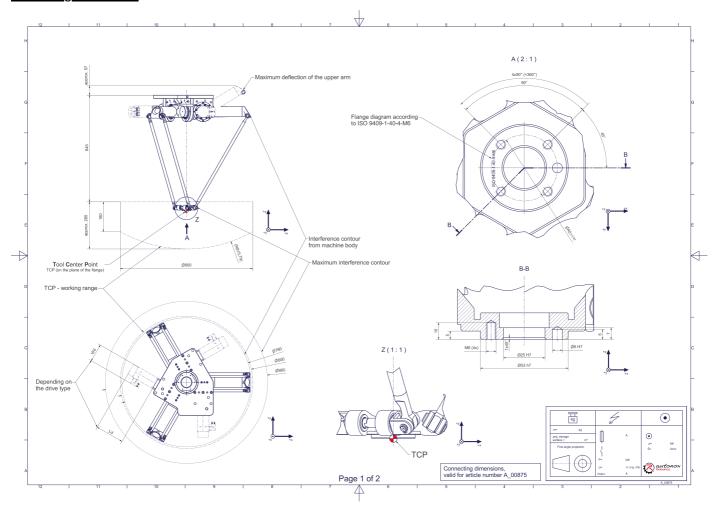
#### **Description:**

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational degrees of freedom.

#### **Scope of delivery:**

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps, Transport and packing instructions

#### **Connecting dimensions:**



<u>Downloads:</u> <u>Connecting dimensions (PDF)</u> <u>3D model (STP)</u> <u>3D model (PDF)</u>



# Product data sheet <a href="https://autonoxfinder.com/en/A\_00875">https://autonoxfinder.com/en/A\_00875</a>

Date of download: Dec 24, 2025 Time of download: 13:55 UTC

#### **Technical specifications:**

Field of application	Standard (not hygienic)
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	3
Rotational Degrees of Freedom ( $\alpha,\beta,\gamma$ )	0
Nominal payload [kg lbs] *	1   2.2
Working area-diameter [mm in]	800   31.5
Working height outside [mm in]	180   7.1
Working height center [mm in]	285   11.2
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Synthetic
Lubricants of the gearboxes	Synthetic
Cleaning	No high pressure
Ambient temperature [°C °F]	0 to +40   +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)

<sup>\*</sup> All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.