



## Technical specifications:

Field of application	Hygienic 'HHD'
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	3
Rotational Degrees of Freedom ( $\alpha, \beta, \gamma$ )	0
Nominal payload [kg lbs] *	12   26.5
Working area-diameter [mm in]	1400   55.1
Working height outside [mm in]	250   9.8
Working height center [mm in]	441   17.4
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Food-grade (FO)
Cleaning	Up to 28 bar   406 psi high pressure
Protection class	IP69K
Ambient temperature [°C °F]	0 to +40   +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)
Robot weight without drive engineering (esp. drive) [kg lbs]	104   229.3
Special features	With stainless steel gearboxes (food-grade lubricants, but therefore reduced performance). To maintain the Hygienic Design requirements, we recommend the use of appropriate stainless steel motors.

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

## Gearbox article number for this robot mechanics:

Function	Article number	Document
Drive of the upper arms	MT_WST00105111-xx-FO	Operating manual gearbox type 3 (PDF)