

## Product data sheet https://autonoxfinder.com/en/A\_00850-FO

Date of download: May 9, 2025 Time of download: 15:03 UTC

### DELTA RLE4-1200-6kg

Article number: A\_00850-FO

**Lubricant variant:** Food-grade lubricants (FO)



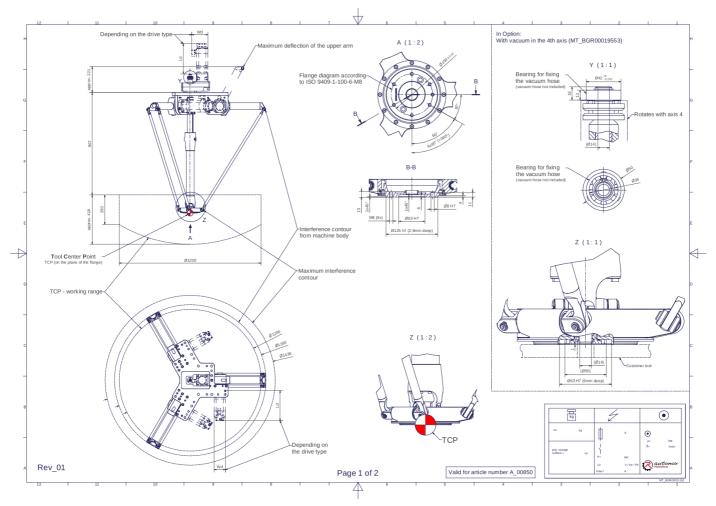
#### **Description:**

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational and one (1) rotational degree(s) of freedom.

#### **Scope of delivery:**

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps, Transport and packing instructions

#### **Connecting dimensions:**



<u>Downloads:</u> <u>Connecting dimensions (PDF)</u> <u>3D model (STP)</u> <u>3D model (PDF)</u>



# Product data sheet https://autonoxfinder.com/en/A 00850-FO

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#### **Technical specifications:**

| Field of application  | Standard (not hygienic)                               |
|---|---|
| Kinematics  | Parallel  |
| Translatory Degrees of Freedom (X,Y,Z)  | 3   |
| Rotational Degrees of Freedom $(\alpha,\beta,\gamma)$                         | 1   |
| Nominal payload [kg lbs] *  | 6   13.2  |
| Working area-diameter [mm in]   | 1200   47.2   |
| Working height outside [mm in]  | 250   9.8   |
| Working height center [mm in]   | 418   16.5  |
| Max. acceleration torque of the rotation y around Z at the output [Nm in.lbs] | 100   885.1   |
| Nominal torque of the rotation y around Z at the output [Nm in.lbs]           | 88   778.9  |
| Max. speed of the rotation y around Z at the output [1/min]                   | 558   |
| Nominal speed of the rotation y around Z at the output [1/min]                | 413   |
| Bearing type of the telescopic shaft(s)                                       | Roller bearing  |
| Bearing type of the arm joints  | Roller bearing  |
| Lubricants of the bearings  | Food-grade (FO)                                       |
| Lubricants of the gearboxes   | Food-grade (FO)                                       |
| Cleaning  | No high pressure                                      |
| Ambient temperature [°C °F]   | 0 to +40   +32 to +104                                |
| Relative humidity level [%]   | 95 (free of condensation)                             |
| Mounting position   | Floor, Ceiling, Wall (on request), Angle (on request) |
| Robot weight without drive engineering (esp. drive) [kg lbs]                  | 65   143.3  |
|   |   |

<sup>\*</sup> All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.