

# DELTA RL4-ATS-1400-3kg

Article number: A\_00849-ATS-FO

Lubricant variant: Food-grade lubricants (FO)



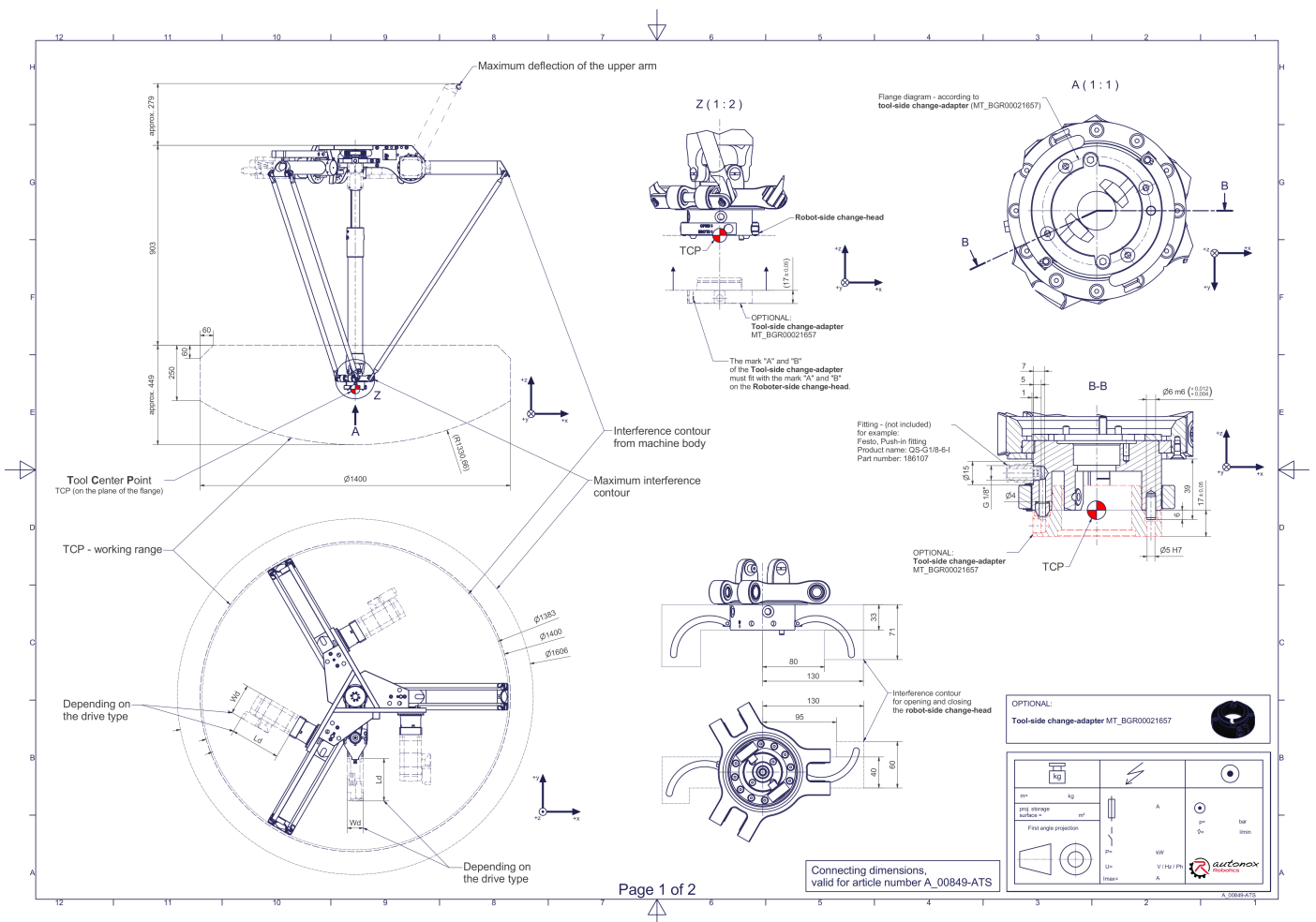
## Description:

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational and one (1) rotational degree(s) of freedom.

## Scope of delivery:

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps, Transport and packing instructions

## Connecting dimensions:



**Downloads:** [Connecting dimensions \(PDF\)](#), [3D model \(STP\)](#), [3D model \(PDF\)](#)

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## Technical specifications:

<b>Field of application</b>	Standard (not hygienic)
<b>Kinematics</b>	Parallel
<b>Translatory Degrees of Freedom (X,Y,Z)</b>	3
<b>Rotational Degrees of Freedom (<math>\alpha, \beta, \gamma</math>)</b>	1
<b>Nominal payload [kg   lbs] *</b>	3   6.6
<b>Working area-diameter [mm   in]</b>	1400   55.1
<b>Working height outside [mm   in]</b>	250   9.8
<b>Working height center [mm   in]</b>	449   17.7
<b>Manual tool changing system ATS</b>	Fourfold media transmission (Compressed air 6 bar   87.0 psi / vacuum -850 mbar   -12.3 psi / min. inner- $\varnothing$ : 4 mm   0.16 in)
<b>Max. acceleration torque of the rotation <math>\gamma</math> around Z at the output [Nm   in.lbs]</b>	40   354.0
<b>Nominal torque of the rotation <math>\gamma</math> around Z at the output [Nm   in.lbs]</b>	33   292.1
<b>Max. speed of the rotation <math>\gamma</math> around Z at the output [1/min]</b>	225
<b>Nominal speed of the rotation <math>\gamma</math> around Z at the output [1/min]</b>	150
<b>Bearing type of the telescopic shaft(s)</b>	Roller bearing
<b>Bearing type of the arm joints</b>	Roller bearing
<b>Lubricants of the bearings</b>	Food-grade (FO)
<b>Lubricants of the gearboxes</b>	Food-grade (FO)
<b>Cleaning</b>	No high pressure
<b>Ambient temperature [<math>^{\circ}</math>C   <math>^{\circ}</math>F]</b>	0 to +40   +32 to +104
<b>Relative humidity level [%]</b>	95 (free of condensation)
<b>Mounting position</b>	Floor, Ceiling, Wall (on request), Angle (on request)

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.