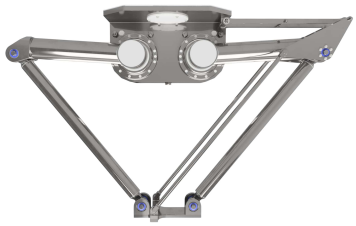
HHD DuoPod RVS2-800-40kg



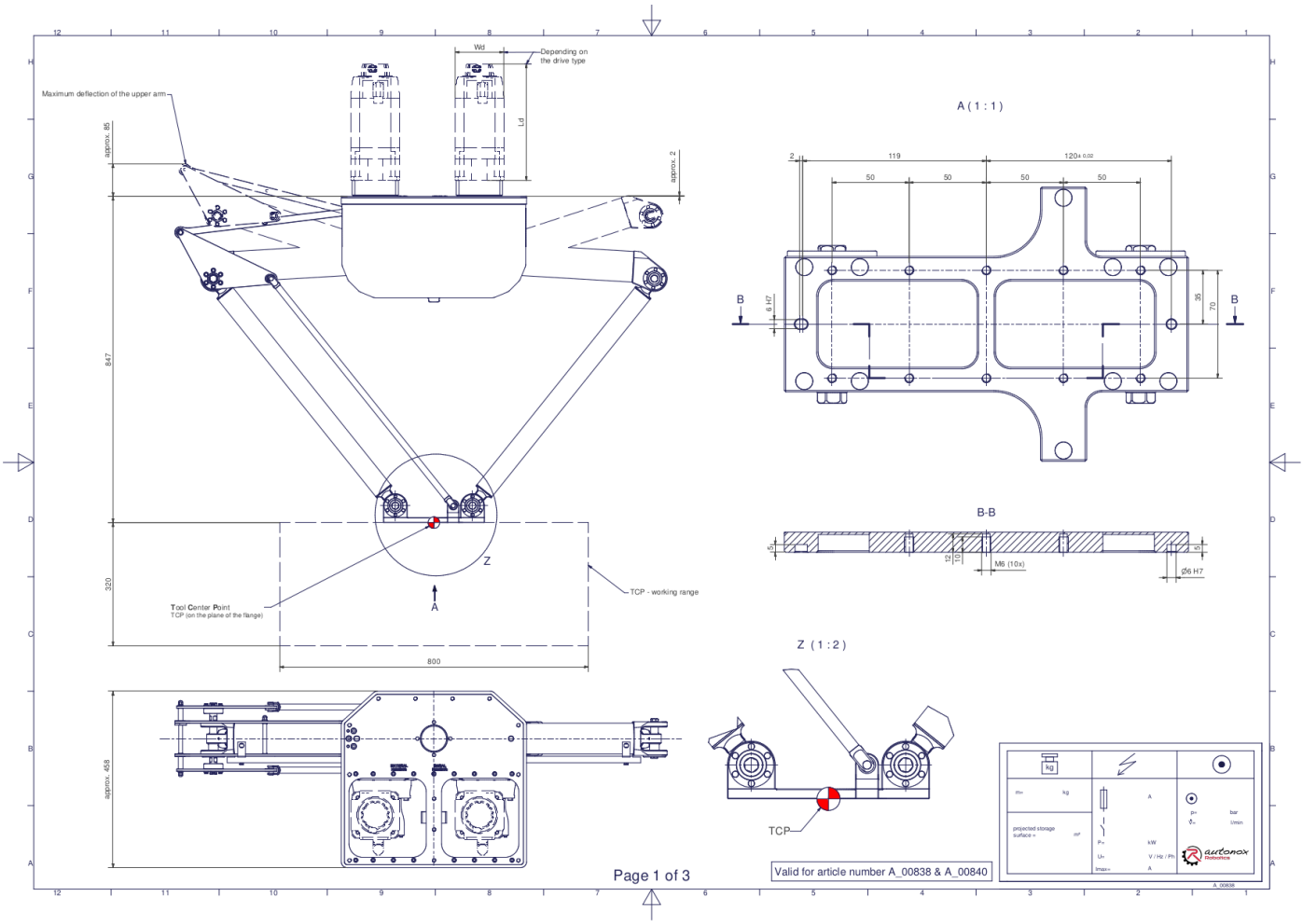
Article number: A_00840

Lubricant variant: Synthetic lubricants

Description:
This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has two (2) translational degrees of freedom.

Scope of delivery:
Robot mechanics incl. gearbox, Servo motor adapter, Transport and packing instructions

Connecting dimensions:



Downloads: Connecting dimensions (PDF) 3D model (STP) 3D model (PDF)

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Technical specifications:

Field of application	Hygienic 'HHD'
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	2
Rotational Degrees of Freedom (α,ß,γ)	0
Nominal payload [kg|lbs] *	40 | 88.2
Working area-width [mm|in]	800 | 31.5
Working height outside [mm|in]	320 | 12.6
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Synthetic
Cleaning	Up to 28 bar | 406 psi high pressure
Protection class	IP69K
Ambient temperature [°C|°F]	0 to +40 | +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Ceiling, Wall (on request), Angle (on request)
Robot weight without drive engineering (esp. motors) [kg|lbs]	120 | 264.6

* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

Gearbox article number for this robot mechanics:

Function	Article number	Document
Drive of the upper arms	MT_BGR00101728-xx	Operating manual gearbox type 4 (PDF)

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