

## HHD DuoPod RVS2-800-40kg

Article number: A\_00840-FO

Lubricant variant: Food-grade lubricants (FO)



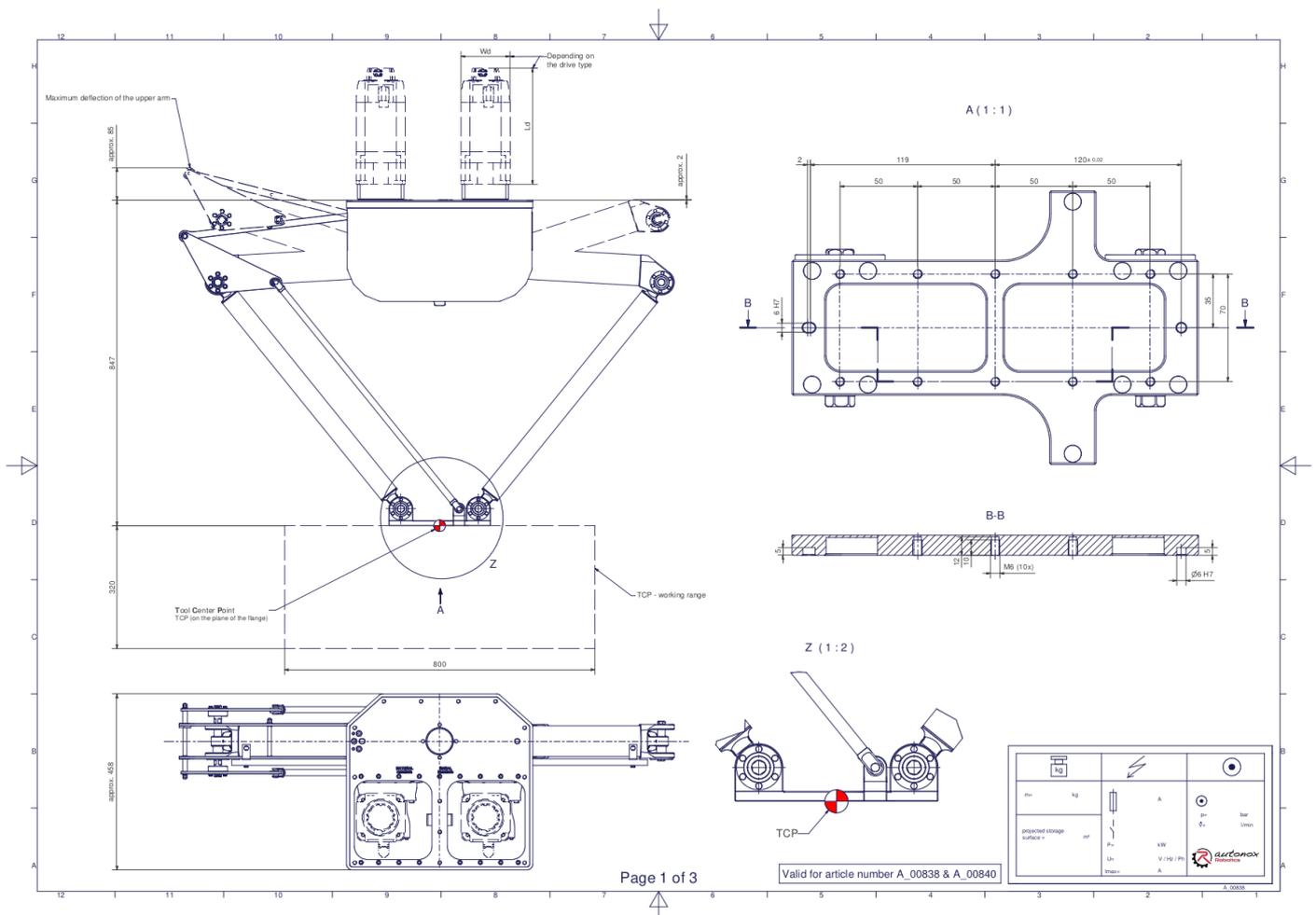
### Description:

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has two (2) translational degrees of freedom.

### Scope of delivery:

Robot mechanics incl. gearbox, Servo motor adapter, Transport and packing instructions

### Connecting dimensions:



**Downloads:** [Connecting dimensions \(PDF\)](#), [3D model \(STP\)](#), [3D model \(PDF\)](#)

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## Technical specifications:

<b>Field of application</b>	Hygienic 'HHD'
<b>Kinematics</b>	Parallel
<b>Translatory Degrees of Freedom (X,Y,Z)</b>	2
<b>Rotational Degrees of Freedom (<math>\alpha,\beta,\gamma</math>)</b>	0
<b>Nominal payload [kg   lbs] *</b>	40   88.2
<b>Working area-width [mm   in]</b>	800   31.5
<b>Working height outside [mm   in]</b>	320   12.6
<b>Bearing type of the arm joints</b>	Roller bearing
<b>Lubricants of the bearings</b>	Food-grade (FO)
<b>Lubricants of the gearboxes</b>	Food-grade (FO)
<b>Cleaning</b>	Up to 28 bar   406 psi high pressure
<b>Protection class</b>	IP69K
<b>Ambient temperature [<math>^{\circ}\text{C}</math>   <math>^{\circ}\text{F}</math>]</b>	0 to +40   +32 to +104
<b>Relative humidity level [%]</b>	95 (free of condensation)
<b>Mounting position</b>	Ceiling, Wall (on request), Angle (on request)
<b>Robot weight without drive engineering (esp. drive) [kg   lbs]</b>	120   264.6

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.