

HHD DuoPod RVS3-800-40kg

Article number: A_00839-FO Lubricant variant: Food-grade lubricants (FO)



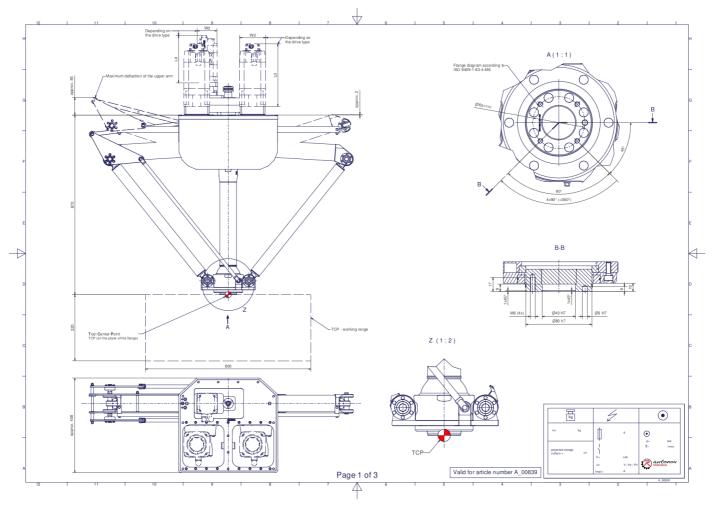
Description:

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has two (2) translational and one (1) rotational degree(s) of freedom.

Scope of delivery:

Robot mechanics incl. gearbox, Servo motor adapter, Transport and packing instructions

Connecting dimensions:



Downloads: Connecting dimensions (PDF) 3D model (STP) 3D model (PDF)

We refer to our General Terms of Sale and Supply and Terms of use.



Technical specifications:

Field of application	Hygienic 'HHD'
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	2
Rotational Degrees of Freedom (α,β,γ)	1
Nominal payload [kg lbs] *	40 88.2
Working area-width [mm in]	800 31.5
Working height outside [mm in]	320 12.6
Max. acceleration torque of the rotation y around Z at the output [Nm in.lbs]	110 973.6
Nominal torque of the rotation y around Z at the output [Nm in.lbs]	110 973.6
Max. speed of the rotation y around Z at the output [1/min]	260
Nominal speed of the rotation y around Z at the output [1/min]	160
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Food-grade (FO)
Cleaning	Up to 28 bar 406 psi high pressure
Protection class	IP69K
Ambient temperature [°C °F]	0 to +40 +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Ceiling, Wall (on request), Angle (on request)
Robot weight without drive engineering (esp. drive) [kg lbs]	144 317.5

* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

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