

# DELTA RL4-1200-12kg

Article number: A\_00832-01-FO

Lubricant variant: Food-grade lubricants (FO)



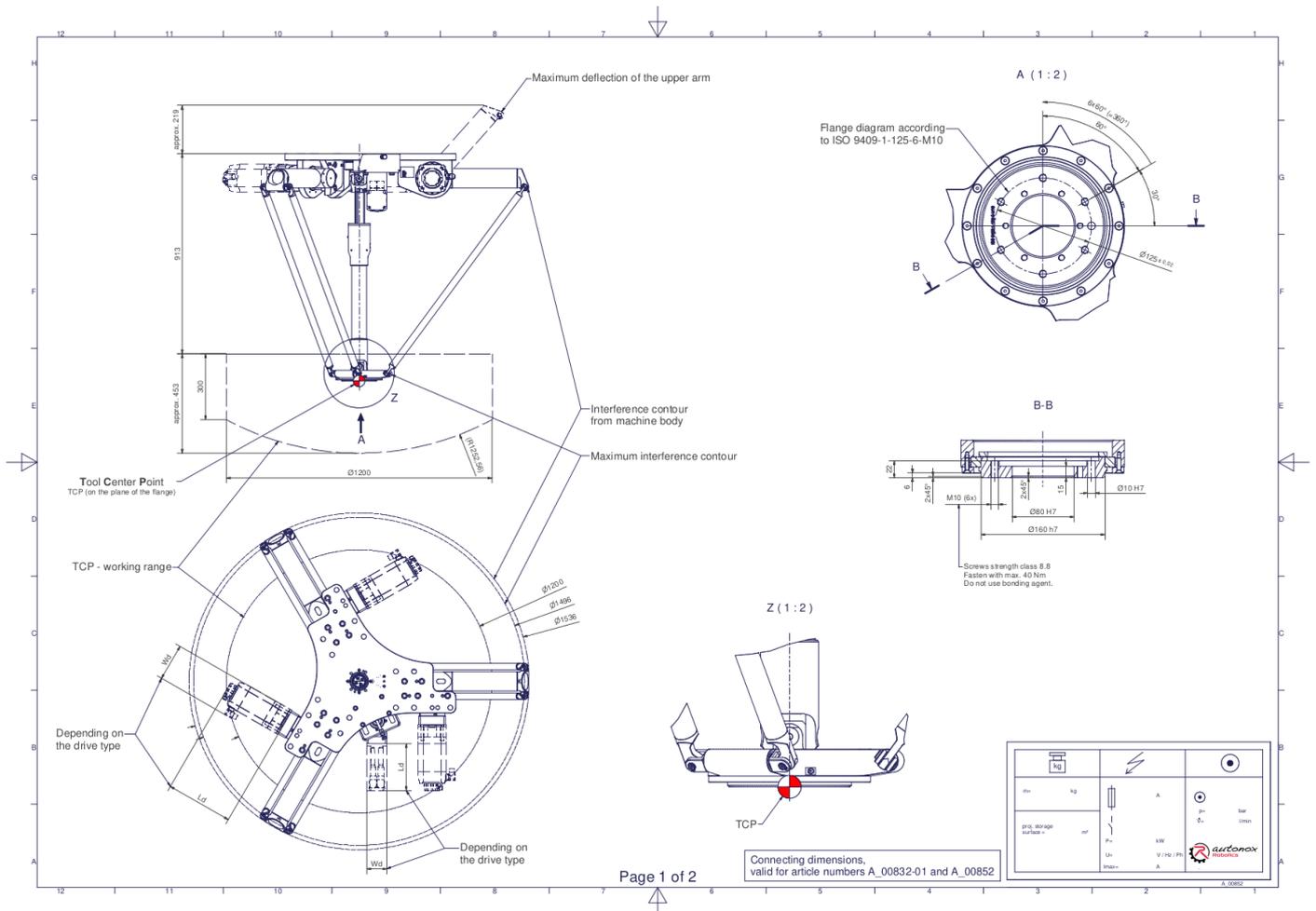
**Description:**

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational and one (1) rotational degree(s) of freedom.

**Scope of delivery:**

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps, Transport and packing instructions

**Connecting dimensions:**



**Downloads:** [Connecting dimensions \(PDF\)](#), [3D model \(STP\)](#), [3D model \(PDF\)](#)

We refer to our [General Terms of Sale and Supply](#) and [Terms of use](#).

## Technical specifications:

Field of application	Standard (not hygienic)
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	3
Rotational Degrees of Freedom ( $\alpha,\beta,\gamma$ )	1
Nominal payload [kg   lbs] *	12   26.5
Working area-diameter [mm   in]	1200   47.2
Working height outside [mm   in]	300   11.8
Working height center [mm   in]	453   17.8
Max. acceleration torque of the rotation $\gamma$ around Z at the output [Nm   in.lbs]	160   1416.1
Nominal torque of the rotation $\gamma$ around Z at the output [Nm   in.lbs]	80   708.1
Max. speed of the rotation $\gamma$ around Z at the output [1/min]	200
Nominal speed of the rotation $\gamma$ around Z at the output [1/min]	135
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Food-grade (FO)
Cleaning	No high pressure
Ambient temperature [ $^{\circ}\text{C}$   $^{\circ}\text{F}$ ]	0 to +40   +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)
Robot weight without drive engineering (esp. drive) [kg   lbs]	96   211.6

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

## Gearbox article number for this robot mechanics:

Function	Article number	Document
Drive of the upper arms	MT_BGR0022174-xx-FO	Operating manual gearbox type 3 (PDF)
Drive of the telescopic shaft for rotation $\gamma$ around Z	MT_BGR00102751-xx-FO	Operating manual gearbox type 1 (PDF)

We refer to our [General Terms of Sale and Supply](#) and [Terms of use](#).