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## **DELTA RL3-T1-1600-50kg**

Article number: A 00824-T1

Lubricant variant: Synthetic lubricants



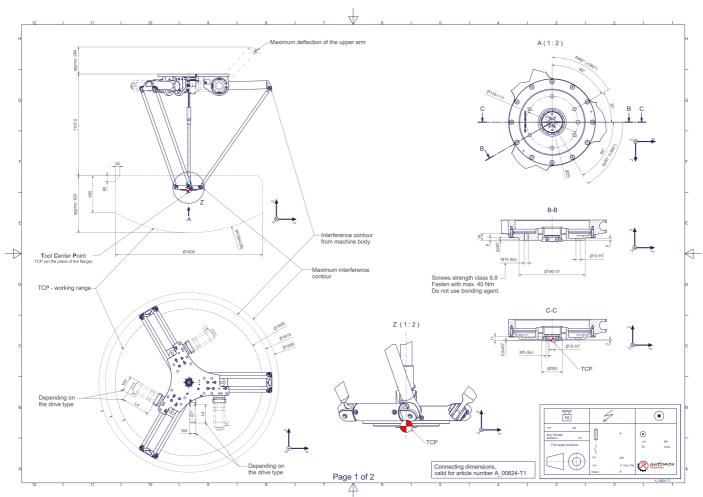
#### **Description:**

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational degrees of freedom.

#### **Scope of delivery:**

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps, Transport and packing instructions

### **Connecting dimensions:**



<u>Downloads:</u> <u>Connecting dimensions (PDF)</u> <u>3D model (STP)</u> <u>3D model (PDF)</u>



# Product data sheet https://autonoxfinder.com/en/A 00824-T1

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#### **Technical specifications:**

| Field of application   | Standard (not hygienic)                               |
|--|---|
| Kinematics   | Parallel  |
| Translatory Degrees of Freedom (X,Y,Z)   | 3   |
| Rotational Degrees of Freedom (α,β,γ)  | 0   |
| Nominal payload [kg lbs] *   | 50   110.2  |
| Working area-diameter [mm in]  | 1600   63.0   |
| Working height outside [mm in]   | 400   15.7  |
| Working height center [mm in]  | 620   24.4  |
| Output type of the tool actuation  | Flange (T)  |
| Number of the tool actuation (telescopic shaft(s))                             | 1   |
| Max. acceleration torque of the tool actuation T/TS1 at the output [Nm in.lbs] | 40   354.0  |
| Nominal torque of the tool actuation T/TS1 at the output [Nm in.lbs]           | 33   292.1  |
| Max. speed of the tool actuation T/TS1 at the output [1/min]                   | 225   |
| Nominal speed of the tool actuation T/TS1 at the output [1/min]                | 150   |
| Bearing type of the telescopic shaft(s)  | Roller bearing  |
| Bearing type of the arm joints   | Roller bearing  |
| Lubricants of the bearings   | Synthetic   |
| Lubricants of the gearboxes  | Synthetic   |
| Cleaning   | No high pressure                                      |
| Ambient temperature [°C °F]  | 0 to +40   +32 to +104                                |
| Relative humidity level [%]  | 95 (free of condensation)                             |
| Mounting position  | Floor, Ceiling, Wall (on request), Angle (on request) |

<sup>\*</sup> All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.