



## Technical specifications:

Field of application	Hygienic 'HHD'
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	3
Rotational Degrees of Freedom ( $\alpha, \beta, \gamma$ )	1
Nominal payload [kg   lbs] *	1   2.2
Working area-diameter [mm   in]	800   31.5
Working height outside [mm   in]	200   7.9
Working height center [mm   in]	275   10.8
Max. acceleration torque of the rotation $\gamma$ around Z at the output [Nm   in.lbs]	6   53.1
Nominal torque of the rotation $\gamma$ around Z at the output [Nm   in.lbs]	4,8   42.5
Max. speed of the rotation $\gamma$ around Z at the output [1/min]	800
Nominal speed of the rotation $\gamma$ around Z at the output [1/min]	460
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Gearbox of the upper arms: Synthetic; gearbox of the telescopic shaft: Food-grade (FO)
Cleaning	Up to 28 bar   406 psi high pressure
Protection class	IP69K
Ambient temperature [°C   °F]	0 to +40   +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Ceiling, Wall (on request), Angle (on request)

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

## Gearbox article number for this robot mechanics:

Function	Article number	Document
Drive of the upper arms	MT_BGR00009592-xx	Operating manual gearbox type 3 (PDF)
Drive of the telescopic shaft for rotation $\gamma$ around Z	MT_WST00104439-xx-FO	Operating manual gearbox type 1 (PDF)

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