Date of download: Sep 15, 2025 Time of download: 21:06 UTC

DELTA RL4-ATS-1600-20kg

Article number: A_00067-ATS-FO

Lubricant variant: Food-grade lubricants (FO)



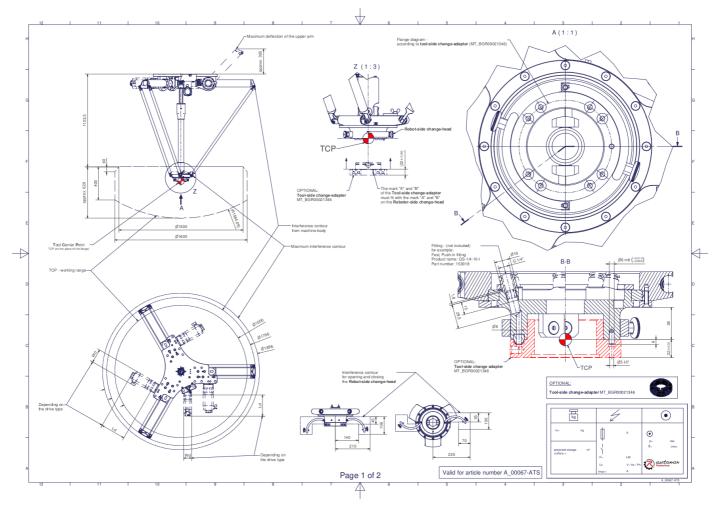
Description:

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational and one (1) rotational degree(s) of freedom.

Scope of delivery:

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps, Transport and packing instructions

Connecting dimensions:



<u>Downloads:</u> <u>Connecting dimensions (PDF)</u> <u>3D model (STP)</u> <u>3D model (PDF)</u>



Product data sheet https://autonoxfinder.com/en/A_00067-ATS-FO

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Technical specifications:

Field of application	Standard (not hygienic)
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	3
Rotational Degrees of Freedom $(\alpha,\!B,\!\gamma)$	1
Nominal payload [kg lbs] *	20 44.1
Working area-diameter [mm in]	1600 63.0
Working height outside [mm in]	400 15.7
Working height center [mm in]	620 24.4
Manual tool changing system ATS	Eightfold media transmission (Compressed air 6 bar 87.0 psi / vacuum -850 mbar -12.3 psi / min. inner-Ø: 6 mm 0.24 in)
Max. acceleration torque of the rotation y around Z at the output [Nm in.lbs]	160 1416.1
Nominal torque of the rotation γ around Z at the output [Nm in.lbs]	80 708.1
Max. speed of the rotation y around Z at the output [1/min]	200
Nominal speed of the rotation y around Z at the output [1/min]	135
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Food-grade (FO)
Cleaning	No high pressure
Ambient temperature [°C °F]	0 to +40 +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)

^{*} All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.