

## Product data sheet https://autonoxfinder.com/en/A\_00066-ATS

Date of download: Nov 7, 2025 Time of download: 01:32 UTC

### DELTA RL3-ATS-1600-20kg

Article number: A\_00066-ATS

Lubricant variant: Synthetic lubricants



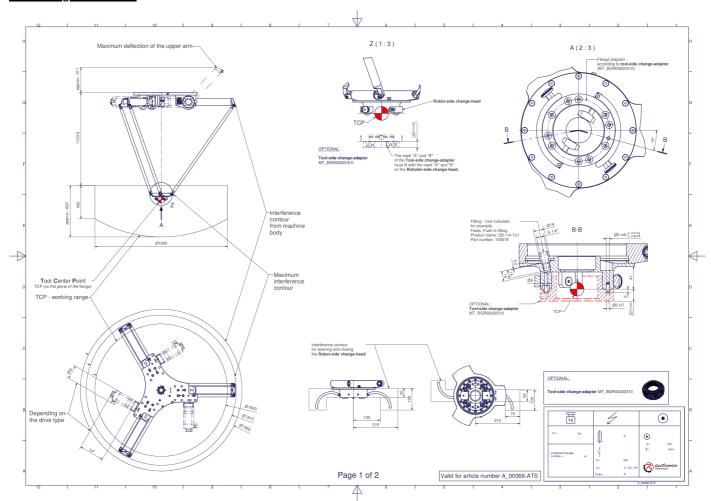
#### **Description:**

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational degrees of freedom.

#### **Scope of delivery:**

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps, Transport and packing instructions

#### **Connecting dimensions:**



<u>Downloads:</u> <u>Connecting dimensions (PDF)</u> <u>3D model (STP)</u> <u>3D model (PDF)</u>



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#### **Technical specifications:**

Field of application	Standard (not hygienic)
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	3
Rotational Degrees of Freedom $(\alpha,\beta,\gamma)$	0
Nominal payload [kg lbs] *	20   44.1
Working area-diameter [mm in]	1600   63.0
Working height outside [mm in]	400   15.7
Working height center [mm in]	620   24.4
Manual tool changing system ATS	Tenfold media transmission (Compressed air 6 bar   87.0 psi / vacuum -850 mbar   -12.3 psi / min. inner-Ø: 6 mm   0.24 in)
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Synthetic
Lubricants of the gearboxes	Synthetic
Cleaning	No high pressure
Ambient temperature [°C °F]	0 to +40   +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)
Robot weight without drive engineering (esp. drive) [kg lbs]	83   183.0

<sup>\*</sup> All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.