

Technical specifications:

| | |
|----------------------------------------------------------------------------------------|-------------------------------------------------------|
| Field of application | Standard (not hygienic) |
| Kinematics | Parallel |
| Translatory Degrees of Freedom (X,Y,Z) | 3 |
| Rotational Degrees of Freedom (α, β, γ) | 1 |
| Nominal payload [kg lbs] * | 20 44.1 |
| Working area-diameter [mm in] | 1400 55.1 |
| Working height outside [mm in] | 350 13.8 |
| Working height center [mm in] | 533 21.0 |
| Output type of the tool actuation | Flange (T) |
| Number of the tool actuation (telescopic shaft(s)) | 1 |
| Max. acceleration torque of the rotation γ around Z at the output [Nm in.lbs] | 240 2124.2 |
| Nominal torque of the rotation γ around Z at the output [Nm in.lbs] | 240 2124.2 |
| Max. speed of the rotation γ around Z at the output [1/min] | 177 |
| Nominal speed of the rotation γ around Z at the output [1/min] | 124 |
| Max. acceleration torque of the tool actuation T/TS1 at the output [Nm in.lbs] | 40 354.0 |
| Nominal torque of the tool actuation T/TS1 at the output [Nm in.lbs] | 23 203.6 |
| Max. speed of the tool actuation T/TS1 at the output [1/min] | 171 |
| Nominal speed of the tool actuation T/TS1 at the output [1/min] | 114 |
| Bearing type of the telescopic shaft(s) | Roller bearing |
| Bearing type of the arm joints | Roller bearing |
| Lubricants of the gearboxes | Synthetic |
| Cleaning | No high pressure |
| Ambient temperature [°C °F] | 0 to +40 +32 to +104 |
| Relative humidity level [%] | 95 (free of condensation) |
| Mounting position | Floor, Ceiling, Wall (on request), Angle (on request) |
| Robot weight without drive engineering (esp. drive) [kg lbs] | 125 275.6 |

* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

Gearbox article number for this robot mechanics:

| Function | Article number | Document |
|--------------------------------------------------------------|---------------------|---------------------------------------|
| Drive of the upper arms | MT_BGR00017292-U-xx | Operating manual gearbox type 3 (PDF) |
| Drive of the telescopic shaft for rotation γ around Z | MT_BGR00018858-xx | Operating manual gearbox type 7 (PDF) |
| Drive of the telescopic shaft for tool actuation T/TS1 | MT_WST00058592-xx | Operating manual gearbox type 6 (PDF) |