

Product data sheet https://autonoxfinder.com/en/A_00036-02-FO

Date of download: Oct 20, 2025 Time of download: 19:06 UTC

DELTA RL4-1200-3kg

Article number: A_00036-02-FO

Lubricant variant: Food-grade lubricants (FO)



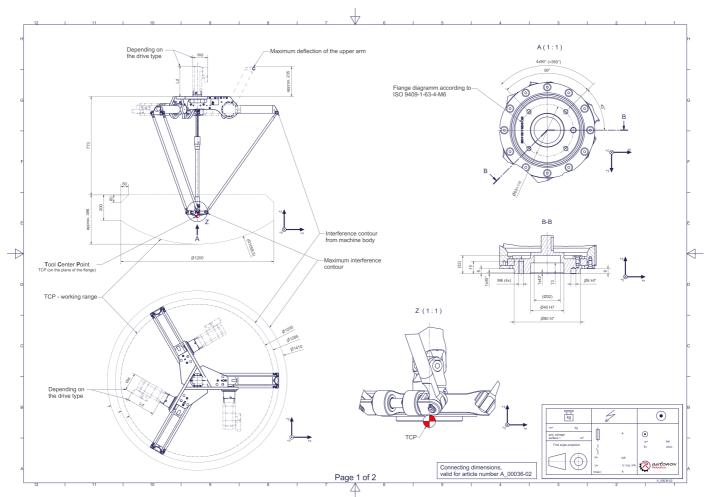
Description:

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational and one (1) rotational degree(s) of freedom.

Scope of delivery:

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps, Transport and packing instructions

Connecting dimensions:



<u>Downloads:</u> <u>Connecting dimensions (PDF)</u> <u>3D model (STP)</u> <u>3D model (PDF)</u>



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Technical specifications:

Field of application	Standard (not hygienic)
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	3
Rotational Degrees of Freedom (α,β,γ)	1
Nominal payload [kg lbs] *	3 6.6
Working area-diameter [mm in]	1200 47.2
Working height outside [mm in]	200 7.9
Working height center [mm in]	386 15.2
Max. acceleration torque of the rotation y around Z at the output [Nm in.lbs]	26,8 237.2
Nominal torque of the rotation γ around Z at the output [Nm \mid in.lbs]	21,6 191.2
Max. speed of the rotation y around Z at the output [1/min]	750
Nominal speed of the rotation y around Z at the output [1/min]	400
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Food-grade (FO)
Cleaning	No high pressure
Ambient temperature [°C °F]	0 to +40 +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)

^{*} All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.

Gearbox article number for this robot mechanics:

Function	Article number	Document
Drive of the upper arms	MT_BGR00015703-xx-FO	Operating manual gearbox type 3 (PDF)
Drive of the telescopic shaft for rotation $\boldsymbol{\gamma}$ around \boldsymbol{Z}	MT_BGR00102787-xx-FO	Operating manual gearbox type 3 (PDF)