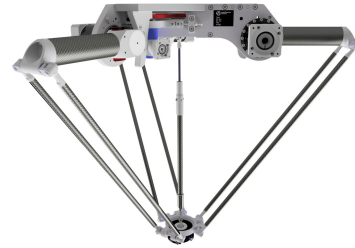


## DELTA RL3-TS1-ATS-900-3kg

**Article number:** A\_00033-TS1-ATS-FO

**Lubricant variant:** Food-grade lubricants (FO)



### **Description:**

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational degrees of freedom.

### **Scope of delivery:**

Robot mechanics incl. gearbox, Servo motor adapter, Threaded protection caps , Transport and packing instructions

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## Technical specifications:

Field of application	Standard (not hygienic)
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	3
Rotational Degrees of Freedom ( $\alpha, \beta, \gamma$ )	0
Nominal payload [kg lbs] *	3   6.6
Working area-diameter [mm in]	900   35.4
Working height outside [mm in]	200   7.9
Working height center [mm in]	317   12.5
Output type of the tool actuation	Shaft (TS)
Number of the tool actuation (telescopic shaft(s))	1
Manual tool changing system ATS	Fourfold media transmission (Compressed air 6 bar   87.0 psi / vacuum -850 mbar   -12.3 psi / min. inner-Ø: 4 mm   0.16 in)
Max. acceleration torque of the tool actuation T/TS1 at the output [Nm in.lbs]	5,5   48.7
Nominal torque of the tool actuation T/TS1 at the output [Nm in.lbs]	5,5   48.7
Max. speed of the tool actuation T/TS1 at the output [1/min]	500
Nominal speed of the tool actuation T/TS1 at the output [1/min]	320
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Food-grade (FO)
Cleaning	No high pressure
Ambient temperature [°C °F]	0 to +40   +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Floor, Ceiling, Wall (on request), Angle (on request)
Robot weight without drive engineering (esp. drive) [kg lbs]	35   77.2

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.