

# HHD DELTA RL4-T1-1000-6kg

Article number: A\_00027-T1-FO

Lubricant variant: Food-grade lubricants (FO)



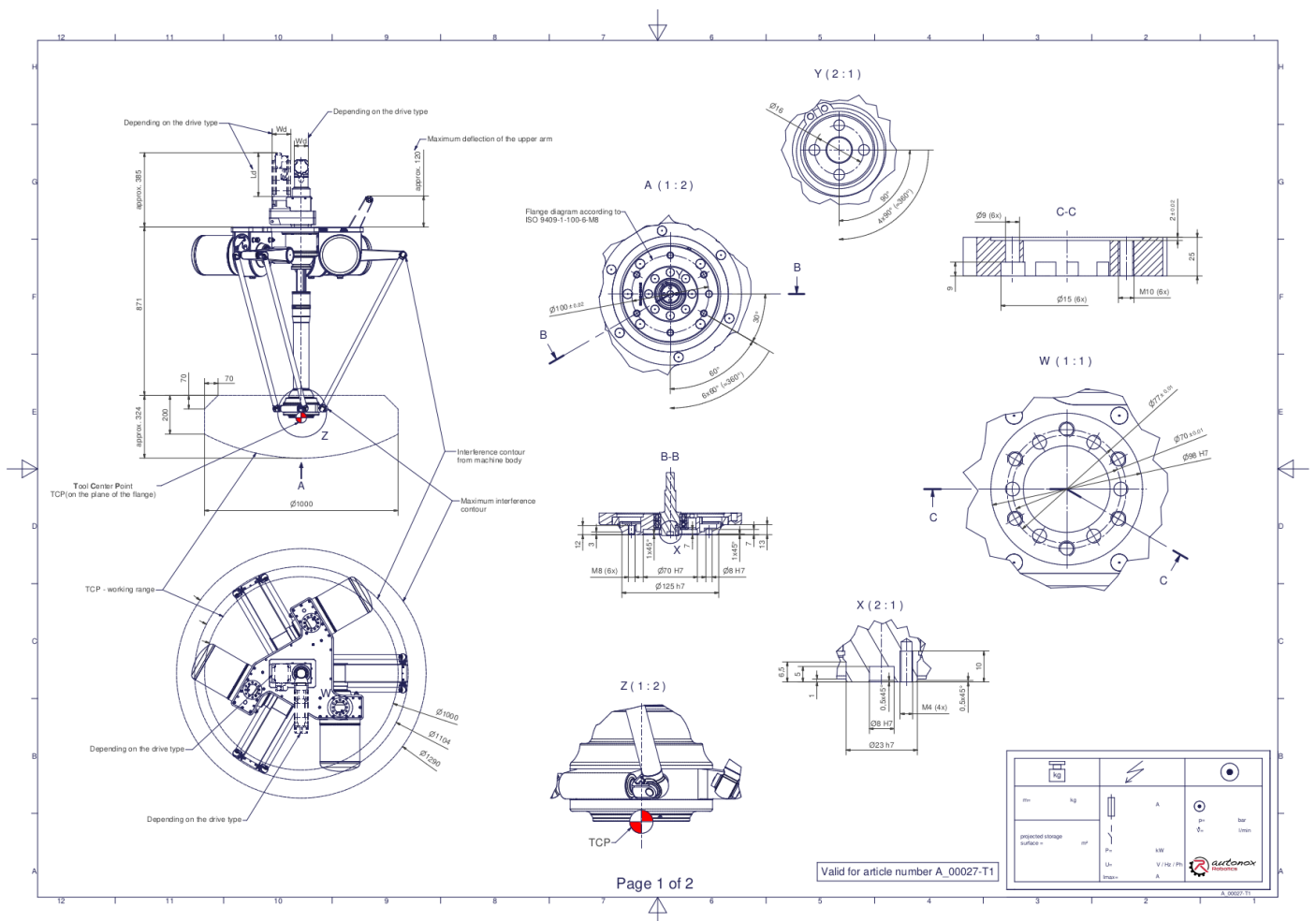
**Description:**

This type of robot is based on the principle of parallel kinematics. All drives are mounted in a fixed position on the robot head. Motor cables are not moved. The robot has three (3) translational and one (1) rotational degree(s) of freedom.

**Scope of delivery:**

Robot mechanics incl. gearbox, Servo motor adapter, Transport and packing instructions

**Connecting dimensions:**



**Downloads:** [Connecting dimensions \(PDF\)](#), [3D model \(STP\)](#), [3D model \(PDF\)](#)

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## Technical specifications:

Field of application	Hygienic 'HHD'
Kinematics	Parallel
Translatory Degrees of Freedom (X,Y,Z)	3
Rotational Degrees of Freedom ( $\alpha, \beta, \gamma$ )	1
Nominal payload [kg   lbs] *	6   13.2
Working area-diameter [mm   in]	1000   39.4
Working height outside [mm   in]	200   7.9
Working height center [mm   in]	324   12.8
Output type of the tool actuation	Flange (T)
Number of the tool actuation (telescopic shaft(s))	1
Max. acceleration torque of the rotation $\gamma$ around Z at the output [Nm   in.lbs]	50   442.5
Nominal torque of the rotation $\gamma$ around Z at the output [Nm   in.lbs]	50   442.5
Max. speed of the rotation $\gamma$ around Z at the output [1/min]	260
Nominal speed of the rotation $\gamma$ around Z at the output [1/min]	160
Max. acceleration torque of the tool actuation T/TS1 at the output [Nm   in.lbs]	9   79.7
Nominal torque of the tool actuation T/TS1 at the output [Nm   in.lbs]	9   79.7
Max. speed of the tool actuation T/TS1 at the output [1/min]	450
Nominal speed of the tool actuation T/TS1 at the output [1/min]	300
Bearing type of the telescopic shaft(s)	Roller bearing
Bearing type of the arm joints	Roller bearing
Lubricants of the bearings	Food-grade (FO)
Lubricants of the gearboxes	Food-grade (FO)
Cleaning	Up to 28 bar   406 psi high pressure
Protection class	IP69K
Ambient temperature [°C   °F]	0 to +40   +32 to +104
Relative humidity level [%]	95 (free of condensation)
Mounting position	Ceiling, Wall (on request), Angle (on request)
Robot weight without drive engineering (esp. drive) [kg   lbs]	131   288.8

\* All given values are nominal values (nominal payload referred to a nominal performance) and can vary under realworld conditions depending on the application (tool specifications, load distances, reduction (partly) of the nominal performance when using food-grade lubricants, ...). Please consider our technical data sheets regarding the load capacity.